

УНИВЕРЗИТЕТ "ГОЦЕ ДЕЛЧЕВ" - ШТИП ФАКУЛТЕТ ЗА ИНФОРМАТИКА

ISSN:1857-8691

ГОДИШЕН ЗБОРНИК 2016/2017 YEARBOOK 2016/2017

ГОДИНА 5

VOLUME V

GOCE DELCEV UNIVERSITY - STIP FACULTY OF COMPUTER SCIENCE

УНИВЕРЗИТЕТ "ГОЦЕ ДЕЛЧЕВ" – ШТИП ФАКУЛТЕТ ЗА ИНФОРМАТИКА



ГОДИШЕН ЗБОРНИК 2016/2017 YEARBOOK 2016/2017

ГОДИНА 5 MAJ, 2017 VOLUME V

ГОДИШЕН ЗБОРНИК ФАКУЛТЕТ ЗА ИНФОРМАТИКА YEARBOOK FACULTY OF COMPUTER SCIENCE

За издавачот:

Проф д-р Цвета Мартиновска Банде

Издавачки совет

Проф. д-р Блажо Боев Проф. д-р Лилјана Колева - Гудева Проф. д-р Цвета Мартиновска Банде Проф. д-р Александра Милева Проф. д-р Зоран Здравев Доц. д-р Билјана Златановска Доц. д-р Александар Крстев

Редакциски одбор

Проф. д-р Цвета Мартиновска Проф. д-р Владо Гичев Проф. д-р Татјана Атанасова - Пачемска Проф. д-р Александра Милева Проф. д-р Зоран Утковски Проф. д-р Зоран Здравев Проф. д-р Сашо Коцески Проф. д-р Наташа Коцеска Проф. д-р Благој Делипетрев Доц. д-р Игор Стојановиќ Доц. д-р Билјана Златановска Доц. д-р Александар Крстев Доц. д-р Наташа Стојковиќ Доц. д-р Доне Стојанов Доц. д-р Мартин Лукаревски

Главен и одговорен уредник Доц. д-р Билјана Златановска

Јазично уредување

Даница Гавриловаска - Атанасовска (македонски јазик) м-р Снежана Кирова (англиски јазик)

Техничко уредување

Славе Димитров Благој Михов

Редакција и администрација

Универзитет "Гоце Делчев"-Штип Факултет за информатика ул. "Крсте Мисирков" 10-А п. фах 201, 2000 Штип Р. Македонија

Editorial board

Prof. Blazo Boev, Ph.D Prof. Liljana Koleva - Gudeva, Ph.D. Prof. Cveta Martinovska Bande, Ph.D. Prof. Aleksandra Mileva, Ph.D. Prof. Zoran Zdravev, Ph.D. Ass. Prof. Biljana Zlatanovska, Ph.D. Ass. Prof. Aleksandar Krstev, Ph.D.

Editorial staff Prof. Cveta Martinovska Bande, Ph.D. Prof. Vlado Gicev. Ph.D. Prof. Tatjana Atanasova - Pacemska, Ph.D. Prof. Aleksandra Mileva, Ph.D. Prof. ZoranUtkovski, Ph.D. Prof. Zoran Zdravev, Ph.D. Prof. Saso Koceski, Ph.D. Prof. Natasa Koceska, Ph.D. Prof. Blagoj Delipetrov, Ph.D. Ass. Prof. Igor Stojanovik, Ph.D. Ass. Prof. Biljana Zlatanovska, Ph.D. Ass. Prof. Aleksandar Krstev, Ph.D. Ass. Prof. Natasa Stojkovik, Ph.D. Ass. Prof. Done Stojanov, Ph.D. Ass. Prof. Martin Lukarevski, Ph.D.

Managing/ Editor in chief

Ass. Prof. Biljana Zlatanovska, Ph.D.

Language editor

Danica Gavrilovska-Atanasovska (macedonian language) Snezana Kirova (english language)

Technical editor

Slave Dimitrov Blagoj Mihov

Address of the editorial office

Goce Delcev University – Stip Faculty of Computer Science Krste Misirkov 10-A PO box 201, 2000 Štip, R. of Macedonia

СОДРЖИНА

мирјана коцалева, александра Ристеска	
ПРАКТИЧНА ПРИМЕНА НА ЕДНО – ДИМЕНЗИОНАЛНАТА	
БРАНОВА РАВЕНКА	5
Aleksandar KRSTEV, Boris KRSTEV	
MATHEMATICAL MODELING AND USING OF THE MATLAB	
DEVELOPED TOOLS FOR INDUSTRIAL PRODUCTION AND	
KINETIC FLOTATION MODELLING	13
Rumen TSANEV MARINOV, Diana KIRILOVA NEDELCHEVA	
,	21
STABILITY RESULTS FOR FIXED POINT ITERATION PROCEDURES	21
Мирјана КОЦАЛЕВА, Цвета МАРТИНОВСКА - БАНДЕ	
СПОРЕДБА НА АЛГОРИТМИ ЗА КЛАСИФИКАЦИЈА	27
Darko CEBOV, Ilija MIHAJLOV, Borjana ARSOVA, Zoran ZDRAVEV	
SERVICE FOR CONTROLLING HOUSEHOLD ELECTRICAL DEVICES	
THROUGH THE INTERNET.	37
Rumen TSANEV MARINOV, Diana KIRILOVA NEDELCHEVA	
INVERSE FUNCTION THEOREM WITH STRONG METRIC REGULARITY	43

INVERSE FUNCTION THEOREM WITH STRONG METRIC REGULARITY Rumen Tsanev Marinov¹, Diana Kirilova Nedelcheva²

¹ Department of Mathematics, Technical University of Varna, Bulgaria marinov r@yahoo.com

² Department of Mathematics, Technical University of Varna, Bulgaria dkondova@aby.bg

Abstract. In this paper we prove an extension of the contraction mapping principle for single-valued mappings dealing with more general assumptions containing modulus instead of pseudo-contractive functions. In [4] A. L. Dontchev and R.T. Rockaffelar suppose the strong metric regularity of set-valued mapping F and the Lipschitz continuity of the function g with given nonnegative constants and prove the strong metric regularity of g+F, while we assume the properties of F and g with modulus functions and prove a generalization of their result.

MSC (2010): 47J07; 49J53; 49K40; 47H10.

Key words: Metric regularity; inverse function theorem; set-valued mapping; generalized equations; fixed point theorem.

1. Introduction

The notion of regular multifunction has emerged out of the pioneering work of Ljusternik and Sobolev [7] through the efforts of several workers. In its initial form it was conceived as a mean for solving equations or inequalities under more or less classical surjectivity assumptions on some approximations ([2], [3], [6], [10], [11], [13], [14]). In [15] Penot prove the equivalence of the definitions for Aubin continuous of the inverse mapping, metric regularity and openness with linear rate of a set-valued mapping for the case when the Lipschitz modulus is not just a constant but it is a function.

In this paper we prove an extension of the contraction mapping principle for single-valued mappings where we use more general assumptions containing modulus instead of pseudo-contractive functions. Using this result we prove an inverse function theorem. We consider the parametric generalized equation

find
$$x \in X$$
 such that $0 \in f(p,x) + F(x)$,

where f is a function, F is a set valued mapping acting from a metric space to another metric space and prove an implicit mapping theorem. Some iterative methods for solving parametric generalized equation can be found in [8],[9], and [12]. The using of a modified variational iteration method for solving nonlinear coupled equations is shown in [5].

In this paper we deal with metric spaces (P,π) for p and a complete metric space (X,ρ) for x. The space (Y,σ) is linear space equipped with *shift-invariant metric* σ for the range of f and g, that is:

$$\sigma(y+z,y'+z) = \sigma(y,y')$$
 for all $y,y',z \in Y$.

In such spaces the standard definitions, e.g. of the ball in X with center x and radius r is defined by:

$$B_r(\overline{x}) = \{x \in X \mid \rho(x, \overline{x}) \le r\}$$

and the distance from a point x to a set C in X is denoted by:

$$d(x,C) = \inf_{x' \in C} \rho(x,x').$$

The subset C of a complete metric space is *closed* when $d(x;C) = 0 \Rightarrow x \in C$. Also a set C is *locally closed* at a point $x \in C$ if there is a neighborhood U of x such that the intersection $C \cap U$ is closed.

The graph of F is the set $gph F = \{(x, y) \in X \times Y | y \in F(x)\}$ and the *inverse* of F is the mapping $F^{-1}: Y \Gamma$ X defined by $F^{-1}(y) = \{x | y \in F(x)\}$.

The *solution mapping* associated with the generalized equation $0 \in f(p, x) + F(x)$ is the potentially set-valued mapping $S: P \Gamma X$ defined by

$$S: p \mapsto \{x \mid f(p,x) + F(x) \ni 0\} \text{ for } p \in P.$$

Graphical localization of S at \overline{p} for \overline{x} , where $\overline{x} \in S(\overline{p})$ is a set-valued mapping with its graph having the form $(Q \times U) \cap \operatorname{gph} S$ for some neighborhoods Q of \overline{p} and U of \overline{x} . The localization is single-valued when this mapping reduces to a function for Q into U. If it is not only single-valued but Lipschitz continuous on Q, we speak of Lipschitz localization.

Definition 1.1. An *modulus* is said to be an increasing function $w:[0,\infty)\to[0,\infty)$, which is continuous in 0 and w(0)=0.

Definition 1.2. A function $f: X \to Y$ is said to be *Lipschitz continuous with modulus function* relative to a set D, if $D \subset \operatorname{int} \operatorname{dom} f$ and there exists a modulus function k, such that

$$\sigma(f(x'), f(x'')) \le k(\rho(x', x'')) \text{ for all } x', x'' \in D,$$

It is said to be a *Lipschitz continuous around* \bar{x} when this holds for some neighborhood D of \bar{x} .

Definition 1.3. A function $f:P \times X \to Y$ is said to be *Lipschitz continuous* with respect to x uniformly in p around $(\overline{p}, \overline{x}) \in \operatorname{int} \operatorname{dom} f$ with modulus function, when there are neighborhoods Q of \overline{p} and U of \overline{x} along with a modulus function k, such that

$$\sigma(f(p,x'), f(p,x'')) \le k\rho(x',x'')$$
 for all $x',x'' \in U$ and $p \in Q$.

Definition 1.4. A set valued mapping $F: X \Gamma Y$ is said to be *metrically regular* at \overline{x} for \overline{y} when $\overline{x} \in F(\overline{y})$ and there is a constant $k \ge 0$ together with neighborhoods U of \overline{x} and V of \overline{y} such that

$$d(x, F^{-1}(y)) \le kd(y, F(x))$$
 for all $(x, y) \in U \times V$.

The infimum of k of all such combinations of k,U and V is called the *regularity modulus* for F at \overline{x} for \overline{y} .

Definition 1.5. A mapping $F: X \Gamma Y$ with $(\overline{p}, \overline{x}) \in \operatorname{gph} F$ is called *strongly regular* at \overline{x} for \overline{y} if its inverse F^{-1} has a Lipschitz localization at \overline{y} for \overline{x} .

Definition 1.6. Consider a function $f: P \times X \to Y$ and a point $(\overline{p}, \overline{x}) \in \operatorname{int} \operatorname{dom} f$. A function $h: X \to Y$ with $\overline{x} \in \operatorname{int} \operatorname{dom} h$ is said to be a *strict estimator* of f with respect to x uniformly in p at $(\overline{p}, \overline{x})$ with modulus μ if $h(\overline{x}) = f(\overline{p}, \overline{x})$ and there exists scalars a and τ such that

$$\sigma(r(p,x'),r(p,x)) \le \mu(\rho(x',x))$$
 for all $x,x' \in B_a(\bar{x})$ and $p \in B_\tau(\bar{p})$,

where r(p,x) = f(p,x) - h(x).

Definition 1.7. A nondecreasing function $\varphi: J \to J$ is said to be a *Bianchini-Grandolfi gauge function* [1] on J, where J is an interval on R_+ containing 0 if

$$s(t) = \sum_{n=0}^{\infty} \varphi^n(t) < \infty$$
, for all $t \in J$.

Here we denote by φ^n to be the n-th iteration of the function $\varphi: J \to J$, where J is an interval on R_+ containing 0, $\varphi^0(t) = t$.

Note that Ptak [16] called a function $\varphi: J \to J$ satisfying the above condition a *rate of convergence* on J and noticed that φ satisfies the following functional equation

$$s(t) = t + s(\varphi(t)).$$

2. Main result

We will prove an extension of the contraction mapping principle for set-valued mappings stated in [4] by A. L. Dontchev and R.T. Rockaffelar. The difference is that we use more general assumptions containing modulus instead of pseudo-contractive multifunctions.

Theorem 2.1. (Contraction mapping principle) Let (X, ρ) be a complete metric space and $\overline{x} \in X$.

Годишен зборник 2016/2017 Yearbook 2016/2017

Consider a single-valued mapping $\Phi: X \to X$. Assume that the increasing function $\varphi: J \to J$, where J is an interval on bR_+ containing 0, is a Bianchini-Grandolfi gauge function. Suppose that there exist a>0 and $r\in J$ and a constant $r\in J$, such that the following assumptions hold:

(a)
$$\rho(\overline{x}, \Phi(\overline{x})) \le r$$
, where $s(r) \le a$;

(b)
$$\rho(\Phi(u), \Phi(v)) \le \varphi(\rho(u, v))$$
 for all $u, v \in B_a(\overline{x})$.

Then Φ has a fixed point in $B_{s(r)}(\overline{x})$; that is, there exists $x \in B_{s(r)}(\overline{x})$ such that $x \in \Phi(x)$.

Proof. We will proceed by induction. Denoting $x^1 = \Phi(\overline{x})$ and consider the sequence

$$x^{k+1} \in \Phi(x^k)$$
 for $k = 1, 2...$

We will prove that this sequence satisfies the following inequalities:

$$\rho(x^k, x^{k+1}) \le \varphi^k(r);$$

$$\rho(x^{k+1}, \overline{x}) \le s(r).$$

We denote $x^0 = \overline{x}$. Then

$$\rho(x^1, \overline{x}) \leq r = \varphi^0(r)$$
.

Now we suppose that there exists

$$x^{k+1} = \Phi(x^k)$$
 3a $k = 0,1...,n-1$.

We will prove that the above mentioned inequalities hold for k = n. Using (b) we have

$$\rho(x^{n}, x^{n+1}) = \rho(x^{n}, \Phi(x^{n})) = \rho(\Phi(x^{n-1}), \Phi(x^{n}))$$

$$\leq \varphi(\rho(x^{n-1}, x^{n})) \leq \varphi(\varphi^{n-1}(r)) = \varphi^{n}(r).$$

Hence

$$\rho(x^{n+1},x^n) \leq \varphi^n(r).$$

By the triangle inequality we have

$$\rho(x^{n+1}, \overline{x}) \le \sum_{k=0}^{n} \rho(x^{k+1}, x^{k}) \le \sum_{k=0}^{n} \varphi^{k}(r) < s(r).$$

Hence $x^{n+1} \in B_{s(r)}(\overline{x})$ and this completes the induction.

Since for all k > m > 1 we have

$$\rho(x^k, x^m) \le \sum_{i=m}^{k-1} \rho(x^{i+1}, x^i) \le \sum_{i=m}^{k-1} \varphi^i(r)$$

and $\varphi(t)$ is Bianchini-Grandolfi gauge function, the sequence $\{x^n\}$ is Cauchy sequence. But X is complete metric space, then $\{x^n\}$ converges to x.

Let $n \to \infty$ in the following inequality

$$\rho(x^{n+1}, \overline{x}) \leq s(r).$$

Then we have

$$\rho(x,\bar{x}) \leq s(r)$$

and consequently $x \in B_{s(r)}(\overline{x})$. Since Φ is continuous and $x^n = \Phi(x^{n-1})$ as $n \to \infty$ we have $x = \Phi(x)$, i.e. x is fixed point for Φ and $x \in B_{s(r)}(\overline{x})$.

Now we will prove that x is unique. Let $\tilde{x} \in X$ and $\tilde{x} = \Phi(\tilde{x})$. Then |

$$\rho(x, \tilde{x}) = \rho(\Phi(x), \Phi(\tilde{x})) \le \varphi(\rho(x, \tilde{x})).$$

By the definition of Bianchini-Grandolfi gauge function we have $\varphi(0) = 0$ and $\varphi(t) < t$ for $\forall t > 0$. By the equality $s(t) = t + s(\varphi(t))$ we have $s(\varphi(t)) < s(t)$. Consequently $\rho(x, x) = 0 \Rightarrow x \equiv x$ and this completes the proof of Theorem 2.1.

The next theorem is a generalization of Theorem 5F.1, p.292 [4].

Theorem 2.2. (Inverse function theorem with strong metric regularity) Let (X, ρ) be a complete metric space, (Y, σ) be a linear space with shift-invariant metric σ and $F: X \Gamma Y$ is a set-valued mapping, $(\overline{x}, \overline{y}) \in \operatorname{gph} F$, U is neighborhood of \overline{x} , V is neighborhood of \overline{y} . The function $g: X \to Y$ is Lipschitz continuous with modulus function μ in U. Let $y \mapsto F^{-1}(y) \cap U$ is Lipschitz function in V with modulus function k and the function $\varphi(t) = k(\mu(t))$, $t \in J$, where J is interval in R_+ , containing 0, is Bianchini-Grandolfi gauge function, such that

$$s(t) = \sum_{n=0}^{\infty} \varphi^n(t) < \infty,$$
 for all $t \in J$.

Let $k^{-1} - \mu$ is increasing function.

Then there exist neighborhoods U' of \overline{x} and V' of \overline{y} such that the mapping

 $y \to (g+F)^{-1}(y) \cap U'$ is Lipschtz function in $g(\bar{x}) + V'$ with modulus function $(k^{-1} - \mu)^{-1}$.

Proof. Let $r(y) = F^{-1}(y) \cap U$, $y \in V$. By the statements in the theorem we have

$$\rho(r(y), r(y')) \le k(\sigma(y, y')), \quad \text{for all } y, y' \in V, \tag{1}$$

$$\sigma(g(x), g(x')) \le \mu(\rho(x, x')), \quad \text{for all } x, x' \in U. \tag{2}$$

Choose a > 0 and b > 0 such that $B_a(\overline{x}) \subset U$, $B_{b+u(a)}(\overline{y}) \subset V$ and

$$s(k(b)) \le a. \tag{3}$$

For all $y \in B_b(g(\overline{x}) + \overline{y})$ and $x \in B_a(\overline{x})$, using that σ shift invariant metric we have

$$\sigma(-g(x)+y,\overline{y}) = \sigma(y,g(x)+\overline{y})$$

$$\leq \sigma(y,g(\overline{x})+\overline{y})+\sigma(g(x),g(\overline{x}))$$

$$\leq b+\mu(\rho(x,\overline{x}))\leq b+\mu(a).$$

Then $-g(x) + y \in V \subset \text{dom } r$. Fix $y \in B_b(g(\overline{x}) + \overline{y})$ and consider the mapping

$$\Phi_{v}: x \mapsto r(-g(x)+y)$$
 for $x \in B_{a}(\overline{x})$.

Using (1), we have

$$\rho(\overline{x}, \Phi_{y}(\overline{x}))$$

$$= \rho(r(\overline{y}), r(-g(\overline{x}) + y))$$

$$\leq k(\sigma(y, \overline{y} + g(\overline{x}))) \leq k(b).$$

By (3) we have $s(k(b)) \le a$ and this showes that assumption (a) of Theorem 2.1 is satisfied. Then for all $u, v \in B_a(\overline{x})$ by (1) and (2) we come to

$$\rho(\Phi_{y}(u), \Phi_{y}(v))
= \rho(r(-g(u) + y), r(-g(v) + y))
= (\sigma(-g(u), -g(v)))
= (\sigma(-g(u) + g(u) + g(v), -g(v) + g(u) + g(v)))
\le k(\sigma(g(u), g(v))) \le k(\mu(\rho(u, v))).$$

Since $k(\mu)$ is increasing Bianchini-Grandolfi gauge function, we have assumption (b) of Theorem 2.1. Now we use Theotem 2.1 for the mapping Φ_y and we conclude that there exists unique fixed point

$$x = \Phi_y(x)$$
 and $x \in B_{s(k(b))}(\overline{x}) \subset B_a(\overline{x})$. Then $x(y) = r(y - g(x(y)))$ and
$$\rho(x(y), x(y'))$$
$$= \rho(r(-g(x(y)) + y), r(-g(x(y')) + y'))$$

$$\leq k(\sigma(y, y') + \sigma(g(x(y)), g(x(y'))))$$

$$\leq k(\sigma(y, y') + \mu(\rho(x(y), x(y')))).$$

Consequently

$$\rho(x(y), x(y')) \le k(\sigma(y, y') + \mu(\rho(x(y), x(y')))).$$

Since k is continuous and increasing function we have

$$k^{-1}(\rho(x(y), x(y'))) \le \sigma(y, y') + \mu(\rho(x(y), x(y'))),$$

$$(k^{-1} - \mu)(\rho(x(y), x(y'))) \le \sigma(y, y').$$

By the continuity of $k^{-1} - \mu$ we come to

$$\rho(x(y), x(y')) \le (k^{-1} - \mu)^{-1} (\sigma(y, y')).$$

But x and y arbitrarily chosen in the corresponding neighborhoods of \overline{x} and \overline{y} . Then the above mentioned relation means that $y \to (g+F)^{-1} \cap V'$ is Lipschitz function in $g(\overline{x}) + V'$ with modulus $(k^{-1} - \mu)^{-1}$.

In [4] A. L. Dontchev and R.T. Rockaffelar suppose the strong metric regularity of F and the Lipschitz continuity of g with given nonnegative constants and prove the strong metric regularity of g+F, while we assume the properties of F and g with modulus functions. So this theorem is a generalization of their result.

3. Conclusion

In this study, under more general assumptions containing modulus instead of pseudo-contractive functions, we examine an extension of the contraction mapping principle for single-valued mappings and inverse function theorem for strong metric regularity mapping. Our results extend and complement many theorems in the literature.

References

- [1] Bianchini R.M., Grandolfi, M.: *Transformazioni di tipo contracttivo generalizzato in uno spazio metrico*, Atti Accad. Naz.Lincei Rend.Cl.Sci.Fiz.Mat.Natur. 45, 212-216, (1968).
- [2] Duong P.C., Tuy, H.: Stability, surjectivity and invertibility of non-differentiable mappings., Acta Vietnam. 3, 89-103, (1978).
- [3] Dolecki S.: A general theory of necessary optimality conditions., J. math. Analysis Applic. 78, 267-308, (1980).
- [4] Dontchev A. L., Rockaffelar, R.T.: *Implicit functions and solution mappings*. Springer, Dordrecht (2009).
- [5] Elsayed M. E. Zayed, Hanan M. Abdel Rahman, On using the modified variational iteration method for solving the nonlinear coupled equations in the mathematical physics, Ricerche di Matematica, 59, 137-159, 2010.
- [6] Hoffman A.: On approximate solutions of systems of linear inequalities, J. Res. natn. Bur. Stand. B 49, 263-265, (1952).
- [7] Ljusternic L.A., Sobolev, V.I.: Elements of functional analysis. Nauka, Moscow (1965).
- [8] Marinov R.T.: Convergence of the method of chords for solving generalized equations, Rediconti del Circolo Matematico di Palermo 58, 11-27, (2009).
- [9] Marinov R.T.: An iterative procedure for solving nonsmooth generalized equations, Serdica Math. J. 34, 441-454, (2008).
- [10] Michel P.: Probléme des inégalites. Applications ála programmation différentielle dans espaces de Banach, C.r.hebd. Séanc. Acad. Sci. Paris A 345, 345-348, (1972).

- [11] Michel P.: Probléme des inégalites. Applications ála programmation et an controle optimal, Bull. Soc. Math. Fr. 101, 413-434, (1973).
- [12] Nedelcheva D. K.: A sequential implicit function theorem for iterative solution of generalized equation involving point-based approximation, Rend. Circ. Mat. Palermo 61,65-78, (2012).
- [13] Penot J.P.: *Inversion droite appplications non linéaires applications*, Coll.Nat.Analyse Numér., La Colle Sur Loup 58-59, (1973); C.r.hebd. Séanc.Acad.Sci.Paris 290, 997-1000, (1980).
- [14] Penot J.P.: On regularity conditions in mathematical programming, Math.Prog.Study 19, 167-199, (1982).
- [15] Penot J.P.: *Metric regularity, Opennesss and Lipschitzian behaviour of multifunctions*, Nonlinear Analysis, Theory, Methods and Applications., Vol.13, No.6, 629-643, (1989).
- [16] Ptak, V.: The rate of convergence of Newton's process, Number. Math. 25, 279-285, (1976).