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Трета меѓународна конференција ЕТИМА Third International Conference ETIMA

PREFACE

The Third International Conference "Electrical Engineering, Technology, Informatics, Mechanical Engineering and Automation – Technical Sciences in the Service of the Economy, Education and Industry" (ETIMA'25), organized by the Faculty of Electrical Engineering at the "Goce Delchev" University – Shtip, represents a significant scientific event that enables interdisciplinary exchange of knowledge and experience among researchers, professors, and experts in the field of technical sciences. The conference was held in an online format and brought together 78 authors from five different countries.

The ETIMA conference aims to establish a forum for scientific communication, encouraging multidisciplinary collaboration and promoting technological innovations with direct impact on modern life. Through the presentation of scientific papers, participants shared the results of their research and development activities, contributing to the advancement of knowledge and practice in relevant fields. The first ETIMA conference was organized four years ago, featuring 40 scientific papers. The second conference took place in 2023 and included over 30 papers. ETIMA'25 continued this scientific tradition, presenting more than 40 papers that reflect the latest achievements in electrical engineering, technology, informatics, mechanical engineering, and automation.

At ETIMA'25, papers were presented that addressed current topics in technical sciences, with particular emphasis on their application in industry, education, and the economy. The conference facilitated fruitful discussions among participants, encouraging new ideas and initiatives for future research and projects.

ETIMA'25 reaffirmed its role as an important platform for scientific exchange and international cooperation. The organizing committee extends sincere gratitude to all participants for their contribution to the successful realization of the conference and its scientific value.

We extend our sincerest gratitude to all colleagues who, through the presentation of their papers, ideas, and active engagement in discussions, contributed to the success and scientific significance of ETIMA'25.

The Organizing Committee of the Conference

ПРЕДГОВОР

Третата меѓународна конференција "Електротехника, Технологија, Информатика, Машинство и Автоматика — технички науки во служба на економијата, образованието и индустријата" (ЕТИМА'25), организирана од Електротехничкиот факултет при Универзитетот "Гоце Делчев" — Штип, претставува значаен научен настан кој овозможува интердисциплинарна размена на знаења и искуства меѓу истражувачи, професори и експерти од техничките науки. Конференцијата се одржа во онлајн формат и обедини 78 автори од пет различни земји.

Конференцијата ЕТИМА има за цел да создаде форум за научна комуникација, поттикнувајќи мултидисциплинарна соработка и промовирајќи технолошки иновации со директно влијание врз современото живеење. Преку презентација на научни трудови, учесниците ги споделуваат резултатите од своите истражувања и развојни активности, придонесувајќи кон унапредување на знаењето и практиката во релевантните области.

Првата конференција ЕТИМА беше организирана пред четири години, при што беа презентирани 40 научни трудови. Втората конференција се одржа во 2023 година и вклучи над 30 трудови. ЕТИМА 25 продолжи со истата научна традиција, презентирајќи повеќе од 40 трудови кои ги отсликуваат најновите достигнувања во областа на електротехниката, технологијата, информатиката, машинството и автоматиката.

На ЕТИМА 25 беа презентирани трудови кои обработуваат актуелни теми од техничките науки, со посебен акцент на нивната примена во индустријата, образованието и економијата. Конференцијата овозможи плодна дискусија меѓу учесниците, поттикнувајќи нови идеи и иницијативи за идни истражувања и проекти.

ЕТИМА'25 ја потврди својата улога како значајна платформа за научна размена и интернационална соработка. Организациониот одбор упатува искрена благодарност до сите учесници за нивниот придонес кон успешната реализација на конференцијата и нејзината научна вредност. Конференцијата се одржа онлајн и обедини седумдесет и осум автори од пет различни земји.

Изразуваме голема благодарност до сите колеги кои со презентирање на своите трудови, идеи и активна вклученост во дискусиите придонесоа за успехот на ЕТИМА'25 и нејзината научна вредност.

Организационен одбор на конференцијата

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IOT-BASED ENVIRONMENTAL CONTROL IN 3D PRINTER ENCLOSURES FOR OPTIMAL PRINTING CONDITIONS

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Abstract

With 3D printing becoming a widespread manufacturing process, maintaining optimal environmental conditions is crucial for achieving high-quality 3D prints. This paper explores an IoT-based environmental control system for 3D printer enclosures, designed to regulate temperature and humidity in real time. This system incorporates sensors, microcontrollers, cloud-based databases and mobile applications in order to maintain the desired 3D printing environment.

The automation of the control of the 3D printing conditions ensures higher-quality prints, improved material consistency and durability, and reduced print failures. Additionally, remote monitoring and mobile alerts provide users with up-to-date knowledge about the current and past environmental parameters, control of settings and additional control and command features.

Experimental results will demonstrate the effectiveness of the climate control system, which in turn highlights the potential for both professional and hobbyist 3D printing applications.

Key words

IoT, ESP32, 3D Printing

Introduction

Over the last decades, additive manufacturing, such as 3D printing, has become a mainstream technology. Its ease of use and relatively low entry prices make it affordable for businesses, as well as technology enthusiasts and hobbyists [1]. Unlike the traditional subtractive manufacturing methods, 3D printing works by building different layers of the digital model, one layer at a time [2]. This provides flexibility and speed in the design and manufacturing process, as well as rapid prototyping and quick revisions. This technology is being widely adopted across various sectors, including aerospace, automotive, robotics, medicine, architecture and consumer goods [3].

3D printing is also a very economical and ecological method of manufacturing, because of its almost waste-free processes. The use of different types of materials like plastics, metals, ceramics, and biomaterials provides a wide range of possibilities. Furthermore, the use of recycled materials, for example, materials derived from recycled plastic bottles provides a secondary use for this polluting material [4]. Despite the many advantages, there are certain challenges when it comes to the use of the 3D printing processes. For 3D printing plastic materials, the quality of the printed parts depends on environmental conditions, machine tolerances, and material quality [5].

Globally, the use of 3D printing is becoming mainstream. 3D printing has revolutionized prototyping and low-volume production across industries [6]. Governments and educational

institutions are promoting 3D printing for STEM education [7]. Military and defense use quickly produced 3D parts for rapid manufacturing and service [8]. With the use of 3D printing continuing to evolve, so does the demand for improved quality and speed [9].

1. Role of the environment parameters in the process of 3D printing

Environmental conditions are crucial in determining the quality, consistency, and success rate of 3D prints [10]. In the FDM (Fused Deposition Modeling) 3D printing process, different layers of extruded plastic are stacked to manufacture a desired model. This type of 3D printing is cheaper and more widespread, because of its simplicity and effectiveness [11]. In comparison to the enclosed and precisely controlled industrial 3D printing machines, many affordable consumer desktop 3D printers are exposed to ambient conditions, which can fluctuate significantly throughout the 3D printing process. These variations in the environmental parameters can affect the material and the process itself [12]. Key environmental parameters that play a crucial role in the 3D printing process are:

- Temperature
- Humidity
- Draft

Temperature is the most important environmental factor that influences the 3D printing process. The relationship between the temperature of the extruded material, and printing platform and ambient temperature needs to be carefully and continuously controlled to have high-quality 3D prints and high success rates [13] [14]. Improper temperature control can cause poor layer adhesion, warping, and cracks. Some 3D printing materials are more prone to warping due to temperature differences, such as ABS, ASA, and Nylon [15]. Humidity also plays a significant role in 3D printing, especially with the use of hygroscopic materials like PLA, PETG, and TPU. These types of 3D printing filaments absorb moisture from the air, which can lead to bubbling, oozing, and overall weak prints [16]. Drafts, convection, and uncontrolled airflow within the 3D printing area directly influence the 3D printing process by providing differential cooling of the 3D printed part [17]. This in turn can cause layer warping and delamination, especially with more temperature-sensitive materials like ABS, ASA, etc.

By carefully and actively controlling these environmental parameters, the quality of the 3D prints can be improved. This can be achieved by enclosing the 3D printer in an enclosure, within which these parameters can be measured and regulated [18] [19] [20] [21]. Combined with the IoT capabilities, such an enclosure can provide greater efficiency and ease of access [22]. By controlling the environmental parameters over an IoT network, faster workflow can be achieved, and groundwork is put in place for further automation, for example 3D printing farm comprised of many 3D printers working simultaneously, thus going a step further towards Industry 4.0 [23].

2. Design of the IoT-based 3D printing enclosure controller

To provide an enclosed environment within which the parameters will be monitored and regulated, an insulated housing is built for the 3D printer. The 3D printer that will be used in this study is the A1 model manufactured by the company Bambu Lab, whose technical characteristics are shown in Table 1. The Bambu Lab A1 with its built-in IoT capabilities, such as device login, device information synchronization, firmware/software updates, user device binding, remote printing, slicing parameter management, cloud slicing, failure detection, and other functions [24], should integrate seamlessly with an IoT-controlled enclosure for synchronized environmental management and remote monitoring.

Table 1 Bambu Lab A1 3D printer technical characteristics

Build Volume:	256 x 256 x 256 mm ³						
Chassis:	Steel + Extruded Aluminum						
Hot End:	All-Metal						
Nozzle:	Stainless Steel						
Max Hot End Temperature:	300 °C						
Nozzle Diameter (Optional):	0.2 mm, 0.4mm, 0.6 mm, 0.8 mm						
Filament Diameter:	1.75 mm						
Max Build Plate	100 °C						
Temperature:							
Max Speed of Toolhead:	500 mm/s						
Max Acceleration of	10000 mm/s ²						
Toolhead:							
Max Hot End Flow:	28 mm³/s @ABS						
Part Cooling Fan:	Closed Loop Control						
Hot End Fan:	Closed Loop Control						
Recommended Filaments	PLA, PETG, TPU, PVA						
Not Recommended Filaments	ABS, ASA, PC, PA, PET, Carbon/Glass Fiber						
	Reinforced Polymer						
Monitoring Camera:	Low-Rate Camera (up to 1080P) Timelapse Supported						
Dimensions:	465 x 410 x 430 mm ³						
Net Weight:	8.3 kg						
Input Voltage:	100-240 VAC, 50/60 Hz						
Max Power:	1300W@220V, 350W@110V						
Display:	3.5 inches 320*240 IPS Touch Screen						
Connectivity:	Wi-Fi, Bambu-Bus						
Storage:	Micro SD Card						
Control Interface:	Touch Screen, APP, PC Application						
Motion Controller:	Dual-Core Cortex M4						

Source: Bambu Lab

The 3D printer enclosure, shown in Figure 2, is constructed from 16mm MDF (Medium Density Fiberboard) sheets, which provide good structural strength and thermal insulation [25]. The access door is made from 8mm PMMA (Poly (methyl methacrylate)) sheet. The enclosure's 520x640x600 mm inside dimensions provide a suitable clearance around the moving parts of the 3D printer.

The microcontroller chosen for the control of environmental parameters is the ESP32. With its 240 MHz processor speed, 34 GPIO pins, as well as built-in Wi-Fi and Bluetooth capabilities, it's a good choice for the IoT-based 3D printing enclosure controller [26].



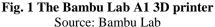




Fig. 2 Enclosure for the 3D printer Source: Author

For the measurement of the environmental parameters, the DHT22 temperature and humidity sensor is chosen. The DHT22 sensor module has a measurable temperature range of -40 to +80°C with ±0.5 °C accuracy and a humidity range of 0 to 100%RH, with an accuracy of 2%RH, which provides a reasonably accurate representation of the desired parameters [27]. For displaying the real-time data measured by the sensor, the IPS 240x240 TFT LCD display module is used. With its 240 by 240-pixel size, it allows the measured data to be displayed, as well as other status and debugging information. The picture shown on the screen of the IPS 240x240 TFT LCD display module is shown in Figure 5. For the heating of the environment, a 360W 220V AC resistive plate heater with a 10A relay module is used. For cooling and ventilation, a 120x120x25mm 12V/0.28A DC fan is used. Separately, for the cooling and ventilation of the 3D printer's processor and control boards, a pair of 40x40x10mm 12V/0.11A DC fans are used. The power for the electronic components is provided by a 12V/5A DC SMPS power supply, as well as a 12V to 5V DC to DC Buck converter. For better visibility inside the enclosure, a string of 12V LED lights is also used. The electronic components are connected as per the circuit diagram shown in Figure 3.

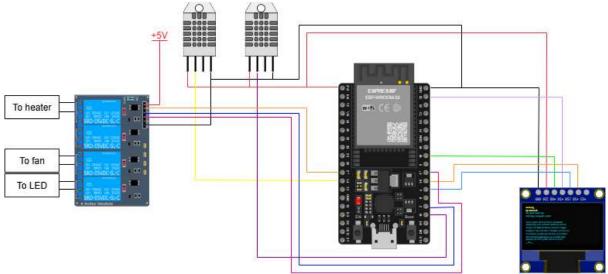


Fig. 3 Circuit diagram of the IoT-based 3D printing enclosure controller Source: Author

As we can see from the circuit diagram, the DHT22 sensors are connected to the ESP32 microcontroller to pins 14 and 15. The LCD display is connected to pins 18, 23, 4, and 16, which provide SPI (Serial Peripheral Interface) communication, as well as reset signal and backlight power. Pin 16 is used for controlling the heating relay, and pin 17 is used for controlling the cooling and ventilation fan. Pin 2 controls the LED lighting in the enclosure.

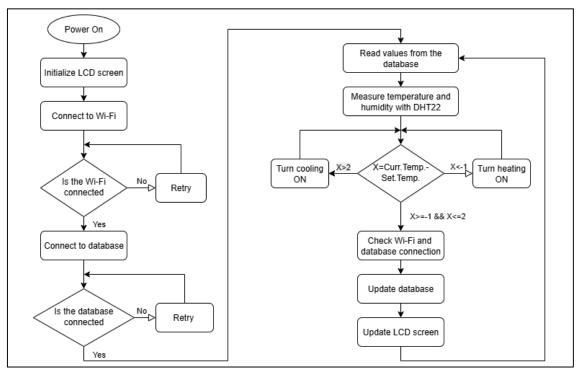


Fig. 4 Control algorithm for the IoT-based 3D printing enclosure controller Source: Author

The algorithm that controls the ESP32 is shown in Figure 4. It consists of the initialization of global variables and functions, after which the LCD screen with its corresponding function library is initialized. The LCD screen is used going forward to ease the process of connecting to the Wi-Fi and Firebase real-time database system. If proper connections are established, then the main function of the controller is initiated. The controller reads the temperature and humidity from the DHT22 sensors and compares them to the pre-set value for the enclosure's ambient temperature. If the enclosure temperature is lower than the set value by more than 2°C, then the heater is turned on until the set temperature is met. For safety reasons, if the control of the heater overshoots the set temperature by 2°C, then the cooling and ventilation fan is activated in order to lower the temperature to the set point. After the proper control of the heater/fan is completed, the connection to the Wi-Fi network and database is checked, and if it passes the check, then the database is updated with the current temperature and humidity of the enclosure. After the database update, the LCD screen is updated to show the current values. The screen update period is 1s, whereas the database update period is 5s, so as for not to overload the database with unnecessary minute changes in the values.

The key aspect of the IoT-based 3D printing enclosure controller is the ability to monitor and control the environmental parameters remotely, by using a mobile application. This application is able to show the current temperature and humidity inside the enclosure, the minimum and maximum temperature and humidity values for a selected period and the temperature of the 3D printer's CPU. Furthermore, this application provides an indication of whether the heating or

cooling is on, and the user can input the set temperature of the enclosure. These values are updated from and to the database, which allows remote control of the temperature in the enclosure. Remote control of the LED lighting is also possible. The GUI (Graphical User Interface) for the 3D printing enclosure controller mobile application is shown in Figure 6.

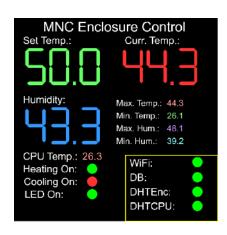




Fig. 5 Data shown on the IPS 240x240 TFT LCD display module
Source: Author

Fig. 6 GUI of the mobile applicationSource: Author

3. Results and discussion

Once everything is assembled, the IoT-based 3D printing enclosure controller can be tested in operation, to verify that it can effectively monitor and regulate the environmental parameters of the enclosure. The test consists of three separate testing phases:

- 1. Baseline test
- 2. Temperature regulation test
- 3. Full operation test

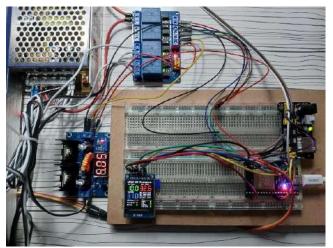


Fig. 7 Testing setup for the IoT-based 3D printing enclosure controller Source: Author

The first test is a baseline test, conducted to ensure proper operation of the sensors and the microcontroller. This test is conducted with a relatively stable room temperature, and all the measured values are monitored and compared to a control thermometer and hygrometer. The collected results of the baseline test are given in Table 2.

Table 2 Baseline test results

	Time	Meas	urements	s with DI	HT22	Control measurements					
			sens	sors							
	HH:M	Temp.	Hum.	m. Temp. Hum.			Hum.	Temp.	Hum.	Room	
	M	Enc.	Enc.	CPU	CPU	Enc.	Enc.	CPU	CPU	Temp.	
1	00:00	27.1	40.8	27.2	41.3	27.4	41.1	27.4	41.1	27.1	
2	00:10	27.1	40.9	27.0	41.0	27.3	41.2	27.3	41.1	27.1	
3	00:20	27.2	40.9	27.1	41.2	27.3	41.1	27.3	41.2	27.1	
4	00:30	27.1	40.8	27.1	41.1	27.3	41.1	27.3	41.2	27.1	
5	00:40	27.2	40.7	27.2	41.2	27.3	41.1	27.3	41.2	27.1	
6	00:50	27.0	40.6	27.1	41.2	27.3	41.1	27.3	41.2	27.1	
7	01:00	27.1	40.8	27.0	41.1	27.3	41.1	27.3	41.2	27.1	
8	01:10	27.2	40.9	27.1	41.0	27.3	41.1	27.3	41.2	27.1	
9	01:20	27.1	40.9	27.1	41.1	27.3	41.1	27.3	41.2	27.2	
10	01:30	27.0	40.8	27.2	41.2	27.3	41.2	27.3	41.2	27.2	

Source: Author

The second test is the temperature regulation test, where a desired temperature of 40°C is set using the mobile application, and the work of the controller is monitored. During this test, the 3D printer was not in operation, but the CPU cooling fans were turned on. The results of the temperature regulation test are given in Appendix A. The graphical representation of the results from the second test is shown in Figure 8. As can be observed, the enclosure temperature is regulated by the controller, and it follows the set temperature of 40°C, within the predefined regulation range of 2°C.

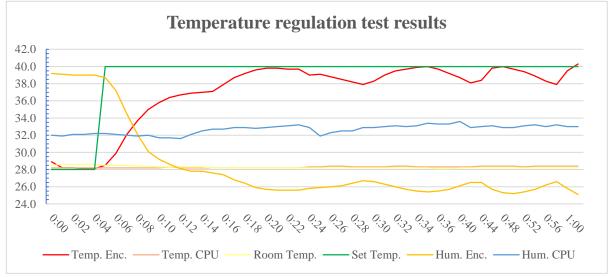


Fig. 8 Graphical representation of temperature regulation test results

Source: Author

The last test is the full operation test. In this test, the 3D printer is turned on and a control test piece is being printed, whilst the enclosure controller regulates the temperature set from the mobile application. The results of the full operation test are given in Appendix B. The graphical representation of the results from the last test is shown in Figure 9. As can be observed, the enclosure temperature is regulated by the controller, and it follows the set temperature of 40° C, within the predefined regulation range of 2° C.

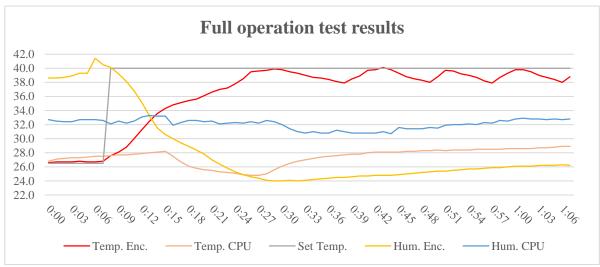


Fig. 9 Graphical representation of the full operation test results Source: Author

4. Conclusion and Future Work

As we can see from the results of the first test, the IoT-based 3D printing enclosure controller does measure temperature and humidity with relatively good accuracy and differentiates from the control thermometer and hygrometer measurements within the accuracy range of the sensor itself.

In the temperature regulation test, we can observe that the IoT-based 3D printing enclosure controller manages to increase the ambient temperature and provide further regulation of the temperature. However, oscillations in the temperature can be observed. This could be the result of the use of natural convection and the bang-bang type of regulation of the temperature. As the results show, a drop in humidity is indicated as the temperature rises, which is helpful in the 3D printing process, especially in printing hygroscopic materials. The results show stability of the CPU's temperature and humidity, which is also a positive result, because these open types of 3D printers are not designed to handle higher ambient temperatures.

The third test, i.e. the full operation test confirms the results of the second test. The IoT-based 3D printing enclosure controller can regulate the ambient temperature with the added heating of the 3D printer in the enclosure.

In the future, a PID temperature regulation is recommended, which will help lower the oscillations of the ambient temperature, as well as a PTC heater with forced convection heating. A more powerful heater could be helpful in achieving the set temperature faster, and allow higher thermal capacity in the whole system. Furthermore, the implementation of a touch screen is necessary to provide the ability to change the set temperature locally without using the mobile application, as well as changing the Wi-Fi network credentials, which for this research were written in the source code. In addition, better insulation of the enclosure is also recommended, which will help mitigate thermal loss due to the thermal conductivity of the build materials and will provide additional sound and vibration insulation. In the human interaction with the IoT

system aspect, push notifications from the mobile application would be practical, as it would allow the user to be notified of wanted and unwanted behavior of the system, such as an overheating event, or a malfunction of a component.

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Appendix A

Table 3 Temperature regulation test results

	Time	Time Measurements with DHT22						Time	Measurements with DHT22					
	1 111116			sensors				1 11116	sensors					
NG	N₂ HH:MM	Temp.	Hum.	Temp.	Hum.	Room	N.C.	нн:мм	Temp.	Hum.	Temp.	Hum.	Room	
745	1111.101101	Enc.	Enc.	CPU	CPU	Temp.	JIY	1111.101101	Enc.	Enc.	CPU	CPU	Temp.	
1	00:00	28.9	39.2	28.2	32.0	28.5	26	00:25	39.1	25.9	28.3	31.9	28.2	
2	00:01	28.2	39.1	28.2	31.9	28.6	27	00:26	38.8	26.0	28.4	32.3	28.2	
3	00:02	28.2	39.0	28.2	32.1	28.6	28	00:27	38.5	26.1	28.4	32.5	28.2	
4	00:03	28.1	39.0	28.2	32.1	28.6	29	00:28	38.2	26.4	28.3	32.5	28.2	
5	00:04	28.1	39.0	28.2	32.2	28.6	30	00:29	37.9	26.7	28.3	32.9	28.2	
6	00:05	28.5	38.7	28.2	32.2	28.5	31	00:30	38.3	26.6	28.3	32.9	28.2	
7	00:06	29.9	37.2	28.2	32.1	28.5	32	00:31	39.0	26.3	28.3	33.0	28.2	
8	00:07	32.1	34.5	28.2	32.0	28.5	33	00:32	39.5	26.0	28.4	33.1	28.2	
9	00:08	33.7	32.1	28.2	31.9	28.4	34	00:33	39.7	25.7	28.4	33.0	28.2	
10	00:09	35.0	30.1	28.2	32.0	28.4	35	00:34	39.9	25.5	28.3	33.1	28.2	
11	00:10	35.8	29.2	28.2	31.7	28.3	36	00:35	40.0	25.4	28.3	33.4	28.2	
12	00:11	36.4	28.6	28.3	31.7	28.3	37	00:36	39.7	25.5	28.3	33.3	28.1	
13	00:12	36.7	28.1	28.2	31.6	28.3	38	00:38	39.2	25.7	28.3	33.3	28.1	
14	00:13	36.9	27.8	28.2	32.1	28.3	39	00:40	38.7	26.1	28.3	33.6	28.2	
15	00:14	37.0	27.8	28.2	32.5	28.3	40	00:42	38.1	26.5	28.3	32.9	28.2	
16	00:15	37.1	27.6	28.2	32.7	28.2	41	00:44	38.4	26.5	28.4	33.0	28.2	
17	00:16	37.9	27.4	28.2	32.7	28.2	42	00:46	39.8	25.7	28.4	33.1	28.2	
18	00:17	38.7	26.8	28.2	32.9	28.2	43	00:48	40.0	25.3	28.4	32.9	28.2	
19	00:18	39.2	26.4	28.2	32.9	28.2	44	00:50	39.7	25.2	28.4	32.9	28.2	
20	00:19	39.6	25.9	28.2	32.8	28.2	45	00:52	39.4	25.4	28.3	33.1	28.2	
21	00:20	39.8	25.7	28.2	32.9	28.2	46	00:54	38.9	25.7	28.4	33.2	28.2	
22	00:21	39.8	25.6	28.2	33.0	28.2	47	00:56	38.3	26.2	28.4	33.0	28.2	
23	00:22	39.7	25.6	28.2	33.1	28.2	48	00:58	37.9	26.6	28.4	33.2	28.2	
24	00:23	39.7	25.6	28.2	33.2	28.2	49	01:00	39.5	25.8	28.4	33.0	28.2	
25	00:24	39.0	25.8	28.3	32.9	28.2	50	01:02	40.3	25.1	28.4	33.0	28.2	

Source: Author

Appendix B

Table 4 Full operation test results

	Time	Measu	rement	s with D	HT22		Time	Measurements with DHT22				
				sors				sensors				
No	HH:MM	Temp.	Hum.	Temp.	Hum.	№	HH:MM	Temp.	Hum.	Temp.	Hum.	
		Enc.	Enc.	CPU	CPU			Enc.	Enc.	CPU	CPU	
1	00:00	26,6	38,6	26,8	32,7	35	00:34	38,7	24,2	27,2	31,0	
2	00:01	26,7	38,6	27,1	32,5	36	00:35	38,6	24,3	27,4	30,8	
3	00:02	26,7	38,7	27,2	32,4	37	00:36	38,4	24,4	27,5	30,8	
4	00:03	26,7	38,9	27,3	32,4	38	00:37	38,1	24,5	27,6	31,2	
5	00:04	26,8	39,3	27,3	32,7	39	00:38	37,9	24,5	27,7	31,0	
6	00:05	26,7	39,3	27,4	32,7	40	00:39	38,5	24,6	27,8	30,8	
7	00:06	26,7	41,4	27,5	32,7	41	00:40	38,9	24,7	27,8	30,8	
8	00:07	26,8	40,5	27,5	32,6	42	00:41	39,7	24,7	28,0	30,8	
9	00:08	27,6	40,1	27,6	32,1	43	00:42	39,8	24,8	28,1	30,8	
10	00:09	28,1	39,2	27,7	32,5	44	00:43	40,1	24,8	28,1	31,0	
11	00:10	28,8	38,1	27,7	32,2	45	00:44	39,8	24,8	28,1	30,7	
12	00:11	30,0	36,8	27,8	32,5	46	00:45	39,3	24,9	28,1	31,6	
13	00:12	31,3	35,1	27,9	33,1	47	00:46	38,8	25,0	28,2	31,4	
14	00:13	32,5	33,2	28,0	33,3	48	00:47	38,5	25,1	28,2	31,4	
15	00:14	33,6	31,5	28,1	33,2	49	00:48	38,3	25,2	28,3	31,4	
16	00:15	34,3	30,6	28,2	33,2	50	00:49	38,0	25,3	28,3	31,6	
17	00:16	34,8	30,0	27,5	31,9	51	00:50	38,8	25,4	28,4	31,5	
18	00:17	35,1	29,4	26,7	32,3	52	00:51	39,7	25,4	28,3	31,9	
19	00:18	35,4	28,9	26,1	32,6	53	00:52	39,6	25,5	28,4	32,0	
20	00:19	35,6	28,4	25,8	32,6	54	00:53	39,2	25,6	28,4	32,0	
21	00:20	36,1	27,8	25,6	32,4	55	00:54	39,0	25,7	28,4	32,1	
22	00:21	36,6	27,0	25,5	32,5	56	00:55	38,7	25,7	28,5	32,0	
23	00:22	37,0	26,4	25,3	32,1	57	00:56	38,2	25,8	28,5	32,3	
24	00:23	37,2	25,8	25,2	32,2	58	00:57	37,9	25,9	28,5	32,2	
25	00:24	37,8	25,3	25,1	32,3	59	00:58	38,7	25,9	28,5	32,6	
26	00:25	38,5	24,9	24,9	32,2	60	00:59	39,3	26,0	28,6	32,5	
27	00:26	39,5	24,6	24,8	32,4	61	01:00	39,8	26,1	28,6	32,8	
28	00:27	39,6	24,4	24,8	32,2	62	01:01	39,8	26,1	28,6	32,9	
29	00:28	39,7	24,1	25,0	32,6	63	01:02	39,5	26,1	28,6	32,8	
30	00:29	39,9	24,0	25,6	32,4	64	01:03	39,0	26,2	28,7	32,8	
31	00:30	39,8	24,0	26,1	32,0	65	01:04	38,7	26,2	28,7	32,7	
32	00:31	39,5	24,1	26,5	31,4	66	01:05	38,4	26,2	28,8	32,8	
33	00:32	39,3	24,0	26,8	31,0	67	01:06	38,0	26,3	28,9	32,7	
34	00:33	39,0	24,1	27,0	30,8	68	01:07	38,8	26,2	28,9	32,8	

Source: Author